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COMPLETE ANALYSIS OF ELECTRODE-TERMINATED CABLES IN TWO-LAYER CONDUCTOR BOUNDED ABOVE BY AIR: CURRENT DENSITY, MAGNETIC FIELD, AND MAGNETIC FIELD GRADIENT

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COASTAL RESEARCH AND TECHNOLOGY DEPARTMENT

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A complete analysis is given for the current density, magnetic field, and magnetic field gradient of a point current source located in the upper layer of a two-layer conductor that is bounded above by air. This problem has a long history, and treatments of varying degrees of completeness and/or rigor are scattered throughout the older geophysical literature. The intent here is to do a complete, self-contained analysis based on potential theory and Ampere's Law; treat all possible cases for the relative conductivity of the media, including the special cases of a lower medium that is an insulator or a perfect conductor; and provide expressions for the magnetic field vector, the current density vector, and the magnetic field gradient tensor in both conducting layers. The effect of performing gradient measurements within an enclosure also is discussed. The principle new results are the inclusion of expressions for the current density and magnetic field in the lower conducting layer, expressions for the magnetic field gradient tensor in both conducting layers, and the analysis of the case of a perfectly conducting lower layer. To complete the set of tools needed to describe a cable terminated by point electrodes, compact general expressions are given for the magnetic field vector and magnetic gradient tensor for a straight current element with arbitrary end points. These are based on the Biot-Savart Law and can be used to calculate the field and gradient contribution from an arbitrary cable joining two or more electrodes by means of superposition. The end results are applicable to such diverse problems as long-wire, electro-prospecting the current distribution around sheet piling protected by active electrodes, and the distributed currents of grounded direct current power systems.					
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INTRODUCTION

The geometry for the following analysis is shown in Figure 1. A point source of current I is located on the z axis at z coordinate h. Space is divided into three regions with electrical conductivities as follows:

$$\sigma = 0, -\infty < z \le 0 \quad (region 0) \tag{1a}$$

$$\sigma = \sigma_1, 0 < z \le d \quad (region 1)$$
 (1b)

$$\sigma = \sigma_2, d < z < \infty \quad (region 2)$$
 (1c)

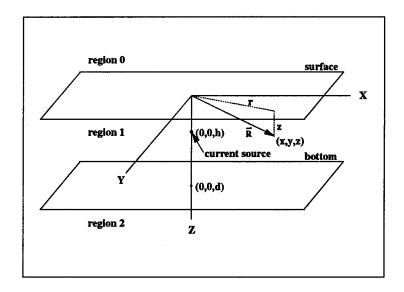


FIGURE 1. GEOMETRY FOR POINT CURRENT SOURCE FIELDS

The source is located in the middle region. It has a potential of the form

$$\Phi_{P} = \frac{I}{4\pi\sigma_{1}\sqrt{r^{2} + (z - h)^{2}}},$$
(2)

which has the integral representation

$$\Phi_P = \frac{I}{4\pi\sigma_1} \int_0^\infty d\lambda J_0(\lambda r) e^{-\lambda|z-h|}.$$
 (3)

Elsewhere, the potential function satisfies Laplace's equation

$$\nabla^2 \Phi(r, \theta, z) = 0, \tag{4}$$

which has the axially symmetric solution in cylindrical coordinates

$$\Phi_H = \int_0^\infty d\lambda J_0(\lambda r) \left[a(\lambda) e^{\lambda z} + b(\lambda) e^{-\lambda z} \right]. \tag{5}$$

The potential in the three regions then has the physically acceptable forms

$$\Phi_0 = \int_0^\infty d\lambda J_0(\lambda r) a_0(\lambda) e^{\lambda z} \quad (-\infty < z \le 0)$$
 (6)

$$\Phi_1 = \int_0^\infty d\lambda J_0(\lambda r) \left[\frac{I}{4\pi\sigma_1} e^{-\lambda |z-h|} + a_1(\lambda) e^{\lambda z} + b_1(\lambda) e^{-\lambda z} \right] \quad (0 < z \le d)$$
 (7)

and

$$\Phi_2 = \int_0^\infty J_0(\lambda r) b_2(\lambda) e^{-\lambda z} \quad (d < z < \infty).$$
 (8)

BOUNDARY CONDITIONS

The boundary conditions require continuity of the normal component of the current density and the tangential component of the electric field at each boundary. The electric field and current density are given by

$$\mathbf{E} = -\nabla \Phi \quad \text{and} \quad \mathbf{J} = \sigma \mathbf{E}. \tag{9}$$

Continuity of the normal current density at each boundary leads to the equations

$$a_1(\lambda) - b_1(\lambda) = -\frac{I}{4\pi\sigma_1} e^{-\lambda h}$$
 (10)

and

$$a_1(\lambda)e^{\lambda d} - b_1(\lambda)e^{-\lambda d} + \varepsilon b_2(\lambda)e^{-\lambda d} = \frac{I}{4\pi\sigma_1}e^{-\lambda(d-h)}$$
(11)

where

$$\varepsilon = \sigma_2/\sigma_1. \tag{12}$$

Continuity of the tangential electric field at the bottom gives the equation

$$a_1(\lambda)e^{\lambda d} + b_1(\lambda)e^{-\lambda d} - b_2(\lambda)e^{-\lambda d} = \frac{I}{4\pi\sigma_1}e^{-\lambda(d-h)}.$$
 (13)

Equations (11),(12), and (13) are sufficient to determine $a_1(\lambda)$, $b_1(\lambda)$, and $b_2(\lambda)$. This allows the computation of all fields in the middle and lower regions, which are of primary interest here. The function $a_0(\lambda)$ can be determined from continuity of the tangential electric field at the air-conductor interface, if needed.

With the introduction of the parameter $Q = (1 - \varepsilon)/(1 + \varepsilon)$, the solutions for the coefficients in the upper and lower conducting regions can be written

$$a_1(\lambda) = \frac{I}{4\pi\sigma_1} \frac{Qe^{-2\lambda d}}{1 - Qe^{-2\lambda d}} (e^{\lambda h} + e^{-\lambda h})$$
(14)

$$b_1(\lambda) = \frac{I}{4\pi\sigma_1} \left[e^{-\lambda h} + \frac{Qe^{-2\lambda d}}{1 - Qe^{-2\lambda d}} (e^{\lambda h} + e^{-\lambda h}) \right]$$
 (15)

and

$$b_2(\lambda) = \frac{I}{4\pi\sigma_2} \frac{(1-Q)(e^{\lambda h} + e^{-\lambda h})}{1 - Qe^{-2\lambda d}}.$$
 (16)

The parameter Q has the range of values $-1 \le Q \le 1$, where Q = 1 corresponds to region 2 being a perfect insulator, Q = 0 corresponds to regions 1 and 2 being identical, and Q = -1 corresponds to region 2 being a perfect conductor.

POTENTIAL AND CURRENT DENSITY

The potential for the middle and lower regions is given by

$$\Phi_1 = \frac{I}{4\pi\sigma_1} \int_0^\infty d\lambda J_0(\lambda r) \left\{ e^{-\lambda |z-h|} + e^{-\lambda(z+h)} \right\}$$
 (17)

$$+\frac{Qe^{-2\lambda d}}{1-Qe^{-2\lambda d}}\left[e^{\lambda(z+h)}+e^{-\lambda(z+h)}+e^{\lambda(z-h)}+e^{-\lambda(z-h)}\right]$$

and

$$\Phi_2 = \frac{I}{4\pi\sigma_2} (1 - Q) \int_0^\infty d\lambda J_0(\lambda r) \left[\frac{e^{-\lambda(z-h)} + e^{-\lambda(z+h)}}{1 - Qe^{-2\lambda d}} \right]. \tag{18}$$

Integrals involving the bessel functions are notoriously difficult to perform numerically. However, a geometric series expansion valid for |Q| < 1

$$\frac{1}{1 - Qe^{-2\lambda d}} = \sum_{n=0}^{\infty} Q^n e^{-2n\lambda d} \tag{19}$$

and the integral representations exemplified by Equations (2) and (3) can be used to write the potential in the upper and lower conductors as

$$\Phi_{1} = \frac{I}{4\pi\sigma_{1}} \left\{ \frac{1}{\sqrt{r^{2} + (z - h)^{2}}} + \frac{1}{\sqrt{r^{2} + (z + h)^{2}}} + \sum_{n=1}^{\infty} Q^{n} \left[\frac{1}{\sqrt{r^{2} + (2nd - z - h)^{2}}} + \frac{1}{\sqrt{r^{2} + (2nd + z + h)^{2}}} + \frac{1}{\sqrt{r^{2} + (2nd + z - h)^{2}}} \right] \right\}$$

$$(20)$$

and

$$\Phi_{2} = \frac{I}{4\pi\sigma_{2}} (1 - Q) \left\{ \frac{1}{\sqrt{r^{2} + (z - h)^{2}}} + \frac{1}{\sqrt{r^{2} + (z + h)^{2}}} + \sum_{n=1}^{\infty} Q^{n} \left[\frac{1}{\sqrt{r^{2} + (2nd + z - h)^{2}}} + \frac{1}{\sqrt{r^{2} + (2nd + z + h)^{2}}} \right] \right\}.$$
(21)

By combining Equation (9) with Equations (20) and (21), expressions for the cartesian components of the current density in the middle and lower regions can be derived. They are

$$J_{1x(y)} = \frac{x(y)I}{4\pi} \left\{ \frac{1}{\sqrt{(r^2 + (z - h)^2)^3}} + \frac{1}{\sqrt{(r^2 + (z + h)^2)^3}} + \sum_{n=1}^{\infty} Q^n \left[\frac{1}{\sqrt{(r^2 + (2nd - z - h)^2)^3}} \right] + \frac{1}{\sqrt{(r^2 + (2nd + z + h)^2)^3}} + \frac{1}{\sqrt{(r^2 + (2nd + z - h)^2)^3}} \right] \right\}$$

$$J_{1z} = \frac{I}{4\pi} \left\{ \frac{|z - h|}{\sqrt{(r^2 + (z - h)^2)^3}} + \frac{z + h}{\sqrt{(r^2 + (z + h)^2)^3}} + \sum_{n=1}^{\infty} Q^n \left[-\frac{2nd - z - h}{\sqrt{(r^2 + (2nd - z - h)^2)^3}} \right] \right\}$$

$$+ \frac{2nd + z + h}{\sqrt{(r^2 + (2nd + z + h)^2)^3}} - \frac{2nd - z + h}{\sqrt{(r^2 + (2nd - z + h)^2)^3}} + \frac{2nd + z - h}{\sqrt{(r^2 + (2nd + z - h)^2)^3}} \right\}.$$
(23)

$$J_{2x(y)} = \frac{x(y)I}{4\pi} (1 - Q) \sum_{n=0}^{\infty} Q^n \left[\frac{1}{\sqrt{(r^2 + (2nd + z - h)^2)^3}} + \frac{1}{\sqrt{(r^2 + (2nd + z + h)^2)^3}} \right]$$
(24)

and

$$J_{2z} = \frac{I}{4\pi} (1 - Q) \sum_{n=0}^{\infty} Q^n \left[\frac{2nd + z - h}{\sqrt{(r^2 + (2nd + z - h)^2)^3}} + \frac{2nd + z + h}{\sqrt{(r^2 + (2nd + z + h)^2)^3}} \right]$$
(25).

MAGNETIC FIELD DUE TO DISTRIBUTED CURRENT

The magnetic field of the distributed current can be constructed by means of a careful application of Ampere's Law, applied to a properly constructed system; that is, one in which charge conservation holds. To accomplish this, the point current source is imagined to be fed by an insulated wire that enters region 1 perpendicular to the boundaries, and extends into medium 0 for a great distance, ultimately returning to a point current sink in region 1 at a great lateral distance from the current source. Application of the Biot-Savart Law to the wire shows that if the wire extends far enough from the boundary in the z direction and returns to the medium sufficiently far away, the magnetic field of the wire segment is indistinguishable from that of a semi-infinite wire extending in the -z direction. In addition, if the current sink is sufficiently far away, its fields are negligible at the current source, and axial symmetry about the incoming wire can be applied. This is illustrated in Figure 2.

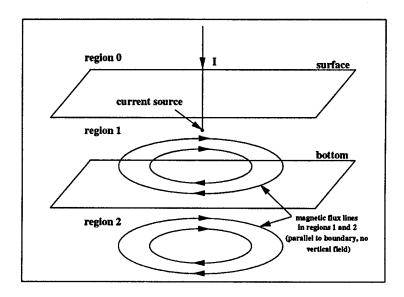


FIGURE 2. MAGNETIC FIELD OF WIRE AND DISTRIBUTED CURRENTS*

Ampere's Law can now be applied to the current distribution. Ampere's Law takes the form

$$\oint \mathbf{H} \cdot d\mathbf{l} = \int \mathbf{J} \cdot d\mathbf{A}, \tag{26}$$

which states that the line integral of the magnetic field around a closed path is equal to the integral of the normal current density over the enclosed surface; that is, the net current through the loop. In the present application, symmetry about the wire axis can be used to write

$$\oint \mathbf{H} \cdot d\mathbf{l} = 2\pi r H_{\Theta} \tag{27}$$

Note that the magnetic field is entirely horizontal, there is no vertical field from the wire current or the distributed currents from the point source.

where r is the radius of a circle centered on the wire axis and H_{θ} is the tangential component of magnetic field on the circle, which is the same everywhere, independent of θ . Now, if the integral on the right hand side of Equation (26) can be evaluated, the magnetic field in regions 1 and 2 can be determined directly. To accomplish this, region 2, $d \le z < \infty$, is first examined, with reference to the notation of Figure 1. The right-hand rule is used to assign the sense of the currents and fields, and then

$$\int \mathbf{J}_{2} \cdot d\mathbf{A} = \int J_{2z} dA = \int_{0}^{2\pi} d\theta \int_{0}^{r} du \, u J_{2z} = 2\pi \int_{0}^{r} du \, u J_{2z}$$
 (28)

where J_{2z} is independent of θ .

Substitution of Equation (25) into Equation (28) and application of Equations (26) and (27) yields

$$H_{2\theta} = \frac{I}{4\pi r} \left\{ 2 - (1 - Q) \left(\frac{z - h}{\sqrt{r^2 + (z - h)^2}} + \frac{z + h}{\sqrt{r^2 + (z + h)^2}} \right) + \sum_{n=1}^{\infty} Q^n \left[\frac{2nd + z - h}{\sqrt{r^2 + (2nd + z - h)^2}} + \frac{2nd + z + h}{\sqrt{r^2 + (2nd + z + h)^2}} \right] \right\}.$$

$$(d \le z < \infty)$$

$$(d \le z < \infty)$$

Repeating this analysis for region 1, for $h < z \le d$, and using Equation (23) instead of Equation (25),

$$H_{1\theta} = \frac{I}{4\pi r} \left\{ 2 - \frac{z - h}{\sqrt{r^2 + (z - h)^2}} - \frac{z + h}{\sqrt{r^2 + (z + h)^2}} + \sum_{n=1}^{\infty} Q^n \left[\frac{2nd - z - h}{\sqrt{r^2 + (2nd - z - h)^2}} \right] - \frac{2nd + z + h}{\sqrt{r^2 + (2nd + z + h)^2}} + \frac{2nd - z + h}{\sqrt{r^2 + (2nd - z + h)^2}} - \frac{2nd + z - h}{\sqrt{r^2 + (2nd + z - h)^2}} \right] \right\}$$

$$(h < z \le d). \tag{30}$$

Next, region 1 is examined for the case $0 \le z < h$. Consistent application of Ampere's Law for this case requires that the contribution of the line current be included, and then

$$2\pi r H_{\theta} = I + 2\pi \int_{0}^{r} du \, u J_{z} \tag{31}$$

and this time substitution from Equation (23) with careful attention to the relative values of z and h, yields

$$H_{1\theta} = \frac{I}{4\pi r} \left\{ 2 - \frac{z - h}{\sqrt{r^2 + (z - h)^2}} - \frac{z + h}{\sqrt{r^2 + (z + h)^2}} + \sum_{n=1}^{\infty} Q^n \left[\frac{2nd - z - h}{\sqrt{r^2 + (2nd - z - h)^2}} \right] - \frac{2nd + z + h}{\sqrt{r^2 + (2nd + z + h)^2}} + \frac{2nd - z + h}{\sqrt{r^2 + (2nd - z + h)^2}} - \frac{2nd + z - h}{\sqrt{r^2 + (2nd + z - h)^2}} \right] \right\}$$

$$(0 \le z < h), \tag{32}$$

which is identical in form to Equation (30), and the magnetic field is continuous at the electrode (z = h) plane, as it must be to be physical.

Now, to isolate the magnetic field due to the electrode distributed currents alone, the Biot-Savart magnetic field of the wire alone is constructed and it is subtracted from the expressions in Equations (29), (30), and (32). Then

$$H_{\theta}^{bs} = \frac{I}{4\pi r} \left[1 - \frac{(z-h)}{\sqrt{r^2 + (z-h)^2}} \right]$$
 (33)

and the electrode magnetic field alone, everywhere in region 1, is given by

$$H_{1\theta}^{e} = \frac{I}{4\pi r} \left\{ 1 - \frac{z+h}{\sqrt{r^{2} + (z+h)^{2}}} + \sum_{n=1}^{\infty} Q^{n} \left[\frac{2nd-z-h}{\sqrt{r^{2} + (2nd-z-h)^{2}}} \right] - \frac{2nd+z+h}{\sqrt{r^{2} + (2nd+z+h)^{2}}} + \frac{2nd-z+h}{\sqrt{r^{2} + (2nd-z+h)^{2}}} - \frac{2nd+z-h}{\sqrt{r^{2} + (2nd+z-h)^{2}}} \right]$$

$$(0 \le z \le d),$$

and in region 2, the field is

$$H_{2\theta}^{e} = \frac{1}{4\pi r} \left\{ 1 + \frac{z - h}{\sqrt{r^{2} + (z - h)^{2}}} - (1 - Q) \sum_{n=0}^{\infty} Q^{n} \left[\frac{2nd + z - h}{\sqrt{r^{2} + 2nd + z - h^{2}}} + \frac{2nd + z + h}{\sqrt{r^{2} + 2nd + z + h^{2}}} \right] \right\}. (35)$$

Then the cartesian components in either region are given by

$$H_x^e = -\frac{y}{r}H_\theta^e \quad \text{and} \quad H_y^e = \frac{x}{r}H_\theta^e. \tag{36}$$

NON-CONDUCTING BOTTOM (O=1)

Region 1

In the limit of a non-conducting bottom, Q = 1, and the series solutions for the fields diverge. To deal with the fields in region 1, the integral expressions defining them will be revisited. The current density is determined from Equations (9) and (17) and has the form

$$J_{1x(y)} = \frac{Ix(y)}{4\pi r} \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \left\{ e^{-\lambda |z-h|} + e^{-\lambda (z+h)} \right\}$$
(37)

$$+\frac{e^{-2\lambda d}}{1-e^{-2\lambda d}}\left[e^{\lambda(z+h)}+e^{-\lambda(z+h)}+e^{\lambda(z-h)}+e^{-\lambda(z-h)}\right]$$

and

$$J_{1z} = \frac{I}{4\pi} \int_{0}^{\infty} d\lambda \lambda J_{0}(\lambda r) \left\{ sgn(z - h)e^{-\lambda |z - h|} + e^{-\lambda (z + h)} + e^{-\lambda (z - h)} \right\}.$$
(38)

The case z > h is explicitly selected. The end result is the same for any case. The expression for the electrode magnetic field is then obtained by combining Equations (26) through (28), (33), and (38). The result is

$$H_{1\theta}^{e} = \frac{I}{4\pi r} \left(-1 + \frac{z - h}{\sqrt{r^{2} + (z - h)^{2}}} + r \int_{0}^{\infty} d\lambda J_{1}(\lambda r) \left\{ e^{-\lambda(z - h)} + e^{-\lambda(z + h)} + e^{-\lambda(z + h)} + e^{-\lambda(z + h)} + e^{-\lambda(z - h)} \right\} \right).$$

$$(39)$$

In each of Equations (37) through (39) a common denominator is used and terms are combined into hyperbolic functions. Then, the fields have the forms

$$J_{1x(y)} = \frac{Ix(y)}{4\pi r} \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \left\{ \frac{\cosh[\lambda(d-z+h)] + \cosh[\lambda(d-z-h)]}{\sinh(\lambda d)} \right\}$$
(40)

$$J_{1z} = \frac{I}{4\pi} \int_{0}^{\infty} d\lambda \lambda J_{0}(\lambda r) \left\{ \frac{\sinh[\lambda(d-z+h)] + \sinh[\lambda(d-z-h)]}{\sinh(\lambda d)} \right\}$$
(41)

and

$$H_{1\theta}^{e} = \frac{I}{4\pi r} \left(-1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}}\right)$$

$$+r \int_{0}^{\infty} d\lambda J_1(\lambda r) \left\{ \frac{\sinh[\lambda(d - z + h)] + \sinh[\lambda(d - z - h)]}{\sinh(\lambda d)} \right\}.$$
(42)

There are three integral types; they are

$$\iota_{1} = \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)}$$

$$\iota_{2} = \int_{0}^{\infty} d\lambda \lambda J_{0}(\lambda r) \frac{\sinh(\lambda a)}{\sinh(\lambda d)}$$
(43)

$$\iota_2 = \int_0^\infty d\lambda \lambda J_0(\lambda r) \frac{\sinh(\lambda a)}{\sinh(\lambda d)} \tag{44}$$

and

$$\iota_3 = \int_0^\infty d\lambda J_1(\lambda r) \frac{\sinh(\lambda a)}{\sinh(\lambda d)}.$$
 (45)

Contour Integration-Residue Theorem. If the integrands of l_1 , l_2 , and l_3 are analytically continued into the complex plane $\lambda \rightarrow w = u + iv$, the denominator $\sinh(wd)$ will have zeros for $wd = in\pi$, where $n = 0, \pm 1, \pm 2, \cdots$. This suggests that the required integrals be related to integrals over a closed contour containing these zeros, and the Cauchy residue theorem be exploited. An appropriate contour is shown in Figure 3. The contour is closed in the upper half plane, and the zeros involved are those for n > 0.

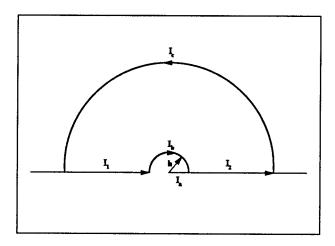


FIGURE 3. INTEGRATION CONTOUR IN w PLANE

The integrals of interest are taken over the interval I_2 in Figure 3, in the limit that I_a goes to 0, and I_2 becomes infinite. This integral will be related to the closed contour integral over the successive intervals I_1 , I_b , I_2 , and I_c . To this end, the integral over I_2 will be expressed in terms of an integral over both I_1 and I_2 . To accomplish this, bessel functions J_n will be expressed in terms of hankel functions. This relationship is analogous to the representation of the cosine function by means of complex exponentials, which is a trick used in fourier transform theory to extend integrals from the positive real axis to the entire real axis. The hankel functions are defined by

$$H_n^{(1)}(z) = J_n(z) + iY_n(z)$$

$$H_n^{(2)}(z) = J_n(z) - iY_n(z)$$
(46)

where Y_n is the bessel function irregular at the origin. The bessel function J_n , which is regular at the origin, now can be expressed as

$$J_n(z) = \frac{1}{2} [H_n^{(1)}(z) + H_n^{(2)}(z)]. \tag{47}$$

Next, it is noted that the hankel functions have the symmetry properties

$$H_0^{(1)}(-z) = -H_0^{(2)}(z)$$

$$H_1^{(1)}(-z) = H_1^{(2)}(z).$$
(48)

Inserting Equation (47) in Equation (43), for example, and using the symmetry properties of all the factors in the integrand, gives

$$\int_{l_{2}} d\lambda \lambda J_{1}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)}$$

$$= \frac{1}{2} \int_{l_{2}} d\lambda \lambda H_{1}^{(1)}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)} + \frac{1}{2} \int_{l_{2}} d\lambda \lambda H_{1}^{(2)}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)}$$

$$= \frac{1}{2} \int_{l_{2}} d\lambda \lambda H_{1}^{(1)}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)} + \frac{1}{2} \int_{-l_{2}} d(-\lambda) (-\lambda) H_{1}^{(2)}(-\lambda r) \frac{\cosh(-\lambda a)}{\sinh(-\lambda d)}$$

$$= \frac{1}{2} \int_{l_{2}} d\lambda \lambda H_{1}^{(1)}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)}$$

$$= \frac{1}{2} \int_{l_{2}} d\lambda \lambda H_{1}^{(1)}(\lambda r) \frac{\cosh(\lambda a)}{\sinh(\lambda d)}$$

where the relation has been used for the intervals $-(-I_2) = I_1$. Thus, the integral over I_2 is replaced by an integral over I_1 and I_2 , with I_1 replaced by $H_1^{(1)}/2$. A similar operation can be done for the integrals in Equations (44) and (45).

Now, using a shorthand notation, relations between the integrals over the various contour segments can be written, where it is understood that the equations hold in the limit that the inner semicircle shrinks to zero, and the outer semicircle recedes to infinity. Then

$$l = \int_{I_1 & I_2} + \int_{I_a} \tag{50}$$

and

$$\oint = \int_{I_1 & I_2} + \int_{I_b} + \int_{I_c}$$
(51)

where \$\delta\$ is the integral around the closed contour. Thus

$$1 = \oint -\int_{I_b} -\int_{I_c} +\int_{I_c} . \tag{52}$$

The following generic results hold for the three integrals of interest.

$$\oint \to 2\pi i \sum_{n=1}^{\infty} S_n \tag{53}$$

$$\int_{I_a} \to 0, \quad \text{(all cases)} \tag{54}$$

$$\int_{I} \to 0, \quad \text{(all cases)} \tag{55}$$

$$\int_{L} \to \text{(simple limit)} \tag{56}$$

Here, the S_n are the residues, defined by

$$\oint dw f(w) = \oint dw \frac{f(w)(w - w_0)}{w - w_0} = \oint dw \frac{g(w)}{w - w_0},$$

$$S_n = \lim_{w \to w_0} g(w) \big|_{w_0 = in\pi/d}.$$
(57)

To establish the limiting values of the various integrals, the limiting forms of the functions involved are examined;

$$J_0(u) \to 1, \quad J_1(u) \to u, \quad u \to 0$$
 (58)

$$\cosh(w) \to 1, \quad \sinh(w) \to w, \quad |w| \to 0 \tag{59}$$

$$H_0^{(1)}(w) \to \frac{2i}{\pi} [\ln(w/2) + \gamma], \quad H_1^{(1)}(w) \to -\frac{2i}{\pi w}, \quad |w| \to 0$$
 (60)

 $(\gamma = 0.5772156649 \cdots \text{Euler's constant})$

and

$$H_0^{(1)}(w) \to \frac{(1-i)e^{iw}}{\sqrt{\pi w}}, \quad H_1^{(1)}(w) \to -\frac{(1+i)e^{iw}}{\sqrt{\pi w}}, \quad |w| \to \infty.$$
 (61)

Applying Equations (58) and (59) to the integrands of ι_1 , ι_2 and ι_3 shows that the integrands approach 0 as λ approaches 0, establishing Equation (54). For the integrals on contour I_c , $w = Re^{i\phi}$, and the hankel function factor in the integrands has the behavior

$$\frac{e^{-rR\sin\phi}}{\sqrt{rR}} \to 0, \quad R \to \infty. \tag{62}$$

The other factors are all proportional to the limiting form

$$e^{(a-d)R|\cos\phi|}, \quad R \to \infty.$$
 (63)

For $\phi = \pi/2$, the associated factors are purely oscillatory, and are dominated by the decaying hankel function factor. For other angles

$$a-d=d-z+h-d=-(z-h)<0$$
, or $a-d=d-z-h-d=-(z+h)<0$ (64)

and the factor vanishes as $R \to \infty$. This establishes Equation (55).

To determine the limiting forms for the integrals over the contour I_b , let $w = h e^{i\phi}$, and explicitly list the integrals. They are

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h^{2} e^{2i\phi} \frac{-2i}{\pi h r e^{i\phi} h d e^{i\phi}} = \frac{1}{\pi r d} \int_{\pi}^{0} d\phi \rightarrow -\frac{1}{r d}, \quad h \rightarrow 0$$
 (65)

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h^{2} e^{2i\phi} \frac{2i}{\pi} \left[\ln \left(\frac{h}{2} e^{i\phi} \right) + \gamma \right] \frac{h a e^{i\phi}}{h d e^{i\phi}} \rightarrow 0, \quad h \rightarrow 0$$
 (66)

and

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h e^{i\phi} \frac{-2i}{\pi h r e^{i\phi}} \frac{h a e^{i\phi}}{h d e^{i\phi}} = \frac{a}{\pi r d} \int_{\pi}^{0} d\phi \rightarrow -\frac{a}{r d}, \quad h \rightarrow 0.$$
 (67)

The residues are constructed using a simple limit process, as indicated in Equation (57). Some useful expressions for the evaluations are

$$\sinh(dw) = \cosh(dw_n)d(w - w_n) + \cdots, \quad w \to w_n$$
 (68)

where dw_n is a zero of $\sinh(dw)$,

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$$\cosh(iu) = \cos(u) \tag{69}$$

$$\sinh(iu) = i\sin(u)$$

and

$$H_0^{(1)}(iu) = -\frac{2i}{\pi} K_0(u)$$

$$H_1^{(1)}(iu) = -\frac{2}{\pi} K_1(u)$$
(70)

where the K_n are the modified bessel functions regular at infinity. Using these results, the residues can be written as

$$\frac{1}{2}wH_1^{(1)}(rw)\frac{\cosh(aw)}{\sinh(dw)}(w-in\pi/d) \to \frac{in\pi}{2d}H_1^{(1)}(in\pi r/d)\frac{\cosh(in\pi a/d)}{(-1)^n d}$$

$$= -\frac{i}{d^2}n(-1)^n K_1(n\pi r/d)\cos(n\pi a/d)$$
(71)

$$\frac{1}{2}wH_0^{(1)}(rw)\frac{\sinh(aw)}{\sinh(dw)}(w-in\pi/d) \to \frac{in\pi}{2d}H_0^{(1)}(in\pi r/d)\frac{\sinh(in\pi a/d)}{(-1)^n d}$$

$$= \frac{i}{d^2}n(-1)^n K_0(n\pi r/d)\sin(n\pi a/d)$$
(72)

and

$$\frac{1}{2}H_1^{(1)}(rw)\frac{\sinh(aw)}{\sinh(dw)}(w-in\pi/d) \to \frac{1}{2}H_1^{(1)}(in\pi r/d)\frac{\sinh(in\pi a/d)}{(-1)^n d}$$

$$= -\frac{i}{\pi d}(-1)^n K_1(n\pi r/d)\sin(n\pi a/d).$$
(73)

Now the explicit forms for the fields can be constructed. In doing so, the arguments of the trigonometric functions are expanded and integral multiples of π are eliminated. Now

$$\iota = \oint -\int_{I_b} \tag{74}$$

and Equations (40) through (42), Equation (53), Equations (65) through (67), and Equations (71) through (73) are combined. The results are

$$J_{1x(y)} = \frac{Ix(y)}{2\pi dr^2} \left(1 + \frac{\pi r}{d} \sum_{n=1}^{\infty} n K_1(n\pi r/d) \left[\cos\{n\pi(z-h)/d\} + \cos\{n\pi(z+h)/d\} \right] \right)$$
(75)

$$J_{1z} = \frac{I}{2d^2} \sum_{n=1}^{\infty} n K_0(n\pi r/d) \left[\sin\{n\pi(z-h)/d\} + \sin\{n\pi(z+h)/d\} \right]$$
 (76)

and, subtracting the Biot-Savart field (Equation (33)),

$$H_{10}^{e} = \frac{I}{4\pi r} \left(1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}} - \frac{2z}{d} \right)$$
 (77)

$$+\frac{\pi r}{d} \sum_{n=1}^{\infty} K_1(n\pi r/d) \left[\sin\{n\pi(z-h)/d\} + \sin\{n\pi(z+h)/d\} \right] \right).$$

Region 2

Inspection of Equations (24), (25), and (35) shows that the fields reduce to the simple forms

$$J_{2x(y)} = 0 \tag{78}$$

$$J_{2z} = 0 \tag{79}$$

and

$$H_{2\theta}^{e} = \frac{I}{4\pi r} \left[1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}} \right]. \tag{80}$$

PERFECTLY CONDUCTING BOTTOM (Q=-1, REGION 1 ONLY)

Region 1

In this case, when the various terms in region 1 are combined to give hyperbolic functions, the resulting integrals are

$$J_{1x(y)} = \frac{Ix(y)}{4\pi r} \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \left\{ \frac{\sinh[\lambda(d-z+h)] + \sinh[\lambda(d-z-h)]}{\cosh(\lambda d)} \right\}$$
(81)

$$J_{1z} = \frac{I}{4\pi} \int_{0}^{\infty} d\lambda \lambda J_{0}(\lambda r) \left\{ \frac{\cosh[\lambda(d-z+h)] + \cosh[\lambda(d-z-h)]}{\cosh(\lambda d)} \right\}$$
(82)

and

$$H_{1\theta}^{\epsilon} = \frac{I}{4\pi} \int_{0}^{\infty} d\lambda J_{1}(\lambda r) \left\{ \frac{\cosh[\lambda(d-z+h)] + \cosh[\lambda(d-z-h)]}{\cosh(\lambda d)} \right\}. \tag{83}$$

The three types of integral now are

$$\iota_{1} = \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \frac{\sinh(\lambda a)}{\cosh(\lambda d)}$$
 (84)

$$\iota_{2} = \int_{0}^{\infty} d\lambda \lambda J_{0}(\lambda r) \frac{\cosh(\lambda a)}{\cosh(\lambda d)}$$
(85)

and

$$\iota_3 = \int_0^\infty d\lambda J_1(\lambda r) \frac{\cosh(\lambda a)}{\cosh(\lambda d)}.$$
 (86)

Again the construct of Equation (49) can be used to introduce the hankel function, and analytic continuation and the residue theorem can be used, where now the singularities occur for

$$z = i(n + 1/2)\pi/d, \quad n = 0, \pm 1, \pm 2, \dots$$
 (87).

Again,

$$1 = \oint -\int_{I_b} -\int_{I_c} +\int_{I_a}$$
 (88)

and, again

$$I_a \to 0$$
 and $I_c \to 0$. (89)

Now, for I_h

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h^{2} e^{2i\phi} \frac{-2i}{\pi h r e^{i\phi}} \frac{ah e^{i\phi}}{1} \to 0$$
 (90)

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h^{2} e^{2i\phi} \left[\frac{2i}{\pi} \ln \left(\frac{hre^{i\phi}}{2} \right) + \gamma \right] \frac{1}{1} \to 0$$
 (91)

$$\frac{1}{2} \int_{\pi}^{0} d\phi i h e^{i\phi} \frac{-2i}{\pi h r e^{i\phi}} \frac{1}{1} \rightarrow -\frac{1}{r}$$
(92)

and for the residues S_n

$$\frac{1}{2}wH_{1}^{(1)}(rw)\frac{\sinh(aw)}{\cosh(dw)}[w-i(n+1/2)\pi/d] \qquad (93)$$

$$\rightarrow \frac{1}{2}[i(n+1/2)\pi/d]H_{1}^{(1)}[i(n+1/2)\pi r/d]\sinh[i(n+1/2)\pi a/d]\frac{1}{i(-1)^{n}d}$$

$$= \frac{i(n+1/2)(-1)^{n+1}}{d^{2}}K_{1}[(n+1/2)\pi r/d]\sin[(n+1/2)\pi a/d]$$

$$\frac{1}{2}wH_{0}^{(1)}(rw)\frac{\cosh(aw)}{\cosh(dw)}[w-i(n+1/2)\pi/d] \qquad (94)$$

$$\rightarrow \frac{1}{2}[(n+1/2)\pi/d]H_{0}^{(1)}[i(n+1/2)\pi r/d]\cosh[i(n+1/2)\pi a/d]\frac{1}{(-1)^{n}d}$$

$$= \frac{i(n+1/2)(-1)^{n+1}}{d^{2}}K_{0}[(n+1/2)\pi r/d]\cos[(n+1/2)\pi a/d]$$

$$\frac{1}{2}H_{1}^{(1)}(rw)\frac{\cosh(aw)}{\cosh(dw)}[w-i(n+1/2)\pi/d]$$

$$\rightarrow \frac{1}{2}H_{1}^{(1)}[i(n+1/2)\pi r/d]\cosh[i(n+1/2)\pi a/d]\frac{1}{i(-1)^{n}d}$$

$$= \frac{i(-1)^{n}}{\pi d}K_{1}[(n+1/2)\pi r/d]\cos[(n+1/2)\pi a/d].$$
(95)

Then, using

$$\iota = \oint -I_b = 2\pi i \sum_{n=1}^{\infty} S_n - I_b \tag{96}$$

gives

$$J_{1x(y)} = \frac{Ix(y)}{2rd^2} \sum_{n=0}^{\infty} (n+1/2)K_1[(n+1/2)\pi r/d]$$
(97)

 $\left\{\cos[(n+1/2)\pi(z-h)/d] + \cos[(n+1/2)\pi(z+h)/d]\right\}$

$$J_{1z} = \frac{I}{2d^2} \sum_{n=0}^{\infty} (n+1/2) K_0[(n+1/2)\pi r/d]$$
(98)

$$\{\sin[(n+1/2)\pi(z-h)/d] + \sin[(n+1/2)\pi(z+h)/d]\}$$

and, again subtracting the Biot-Savart field (Equation (33)),

$$H_{1\theta} = \frac{I}{4\pi r} \left(1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}} - \frac{2r}{d} \sum_{n=0}^{\infty} K_1[(n + 1/2)\pi r/d]\right)$$
(99)

$$\{\sin[(n+1/2)\pi(z-h)/d] + \sin[(n+1/2)\pi(z+h)/d]\}).$$

Region 2

In region 2, the integral forms for the fields are

$$J_{2x(y)} = \frac{x(y)I}{2\pi r} \int_{0}^{\infty} d\lambda \lambda J_{1}(\lambda r) \left[\frac{e^{-\lambda(z+h)} + e^{-\lambda(z-h)}}{1 + e^{-2\lambda d}} \right]$$
(100)

$$J_{2z} = \frac{I}{2\pi} \int_{0}^{\infty} d\lambda \lambda J_0(\lambda r) \left[\frac{e^{-\lambda(z+h)} + e^{-\lambda(z-h)}}{1 + e^{-2\lambda d}} \right]$$
(101)

and

$$H_{2\theta}^{e} = \frac{I}{4\pi r} \left\{ -1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}} \right\}$$

$$(102)$$

$$+2r\int_{0}^{\infty}d\lambda J_{1}(\lambda r)\left[\frac{e^{-\lambda(z+h)}+e^{-\lambda(z-h)}}{1+e^{-2\lambda d}}\right]\}.$$

In these integrals, the denominator can be converted to a hyperbolic cosine, but the numerators will be linear combinations of hyperbolic sine and cosine functions. Some of the terms can be rewritten using a construct similar to Equation (49), and can be treated with contour integration techniques. However, the remaining terms do not have the appropriate symmetry to accomplish this. These remaining terms have symmetry such that the integral can be extended over the real axis while retaining the bessel function form, and there is no singularity at the origin as there is with the hankel function. However, when the integrands of these terms are analytically continued into the complex plane, the bessel functions diverge in either half plane, and the outer contour cannot be closed. Thus, there is no way to explicitly evaluate these integrals. As this particular case is more of a curiosity without practical significance, it will not be pursued further.

DISTRIBUTED CURRENT MAGNETIC FIELD GRADIENT

The magnetic field gradients due to the electrode distributed currents can be expressed in terms of the r and z derivatives of the magnetic field expressions already obtained in Equations (34), (35), (77), (80), and (99). First

$$H_x^e = -H_\theta^e \sin \theta = -\frac{y}{r} H_\theta^e \tag{103}$$

and

$$H_{y}^{e} = H_{\theta}^{e} \cos \theta = \frac{x}{r} H_{\theta}^{e}. \tag{104}$$

Then, for the diagonal gradients

$$\frac{\partial H_x^e}{\partial x} = \frac{xy}{r^3} - \frac{y}{r} \frac{\partial H_\theta^e}{\partial x} = \frac{xy}{r^2} \left(\frac{H_\theta^e}{r} - \frac{\partial H_\theta^e}{\partial r} \right)$$
 (105)

and

$$\frac{\partial H_y^e}{\partial y} = -\frac{\partial H_x^e}{\partial x},\tag{106}$$

the latter following from $\nabla \cdot \mathbf{H}^e = 0$ and $H_z^e = 0$ ($\nabla \cdot \mathbf{H} = 0$ and below, it is shown that $\nabla \cdot \mathbf{H}^{BS} = 0$).

For the off-diagonal gradients, the non-zero terms are

$$\frac{\partial H_x^e}{\partial z} = -\frac{y}{r} \frac{\partial H_\theta^e}{\partial z} \tag{107}$$

$$\frac{\partial H_y^e}{\partial z} = \frac{x}{r} \frac{\partial H_\theta^e}{\partial z} \tag{108}$$

$$\frac{\partial H_x^e}{\partial y} = -\left[\frac{x^2}{r^3} H_\theta^e + \frac{y^2}{r^2} \frac{\partial H_\theta^e}{\partial r} \right]$$
 (109)

and

$$\frac{\partial H_{y}^{e}}{\partial x} = \left[\frac{y^{2}}{r^{3}} H_{\theta}^{e} + \frac{x^{2}}{r^{2}} \frac{\partial H_{\theta}^{e}}{\partial r} \right]. \tag{110}$$

CONDUCTING BOTTOM

Region 1

From Equation (34)

$$\frac{\partial H_{1\theta}^{\epsilon}}{\partial r} = -\frac{H_{1\theta}^{\epsilon}}{r} + \frac{I}{4\pi} \left[\frac{z+h}{\sqrt{(r^2 + (z+h)^2)^3}} + \sum_{n=1}^{\infty} Q^n \left\{ -\frac{2nd-z-h}{\sqrt{(r^2 + (2nd-z-h)^2)^3}} + \frac{2nd+z+h}{\sqrt{(r^2 + (2nd+z+h)^2)^3}} - \frac{2nd-z+h}{\sqrt{(r^2 + (2nd-z+h)^2)^3}} + \frac{2nd+z-h}{\sqrt{(r^2 + (2nd+z-h)^2)^3}} \right\} \right].$$
(111)

and

$$\frac{\partial H_{10}^{e}}{\partial z} = \frac{I}{4\pi r} \left[\frac{(z+h)^{2}}{\sqrt{(r^{2}+(z+h)^{2})^{3}}} - \frac{1}{\sqrt{r^{2}+(z+h)^{2}}} + \sum_{n=1}^{\infty} Q^{n} \left\{ \frac{(2nd-z-h)^{2}}{\sqrt{(r^{2}+(2nd-z-h)^{2})^{3}}} + \frac{(2nd+z+h)^{2}}{\sqrt{(r^{2}+(2nd+z+h)^{2})^{3}}} + \frac{(2nd-z+h)^{2}}{\sqrt{(r^{2}+(2nd+z+h)^{2})^{3}}} + \frac{(2nd+z-h)^{2}}{\sqrt{(r^{2}+(2nd+z-h)^{2})^{3}}} - \frac{1}{\sqrt{r^{2}+(2nd-z+h)^{2}}} - \frac{1}{\sqrt{r^{2}+(2nd+z+h)^{2}}} - \frac{1}{\sqrt{r^{2}+(2nd-z+h)^{2}}} - \frac{1}{\sqrt{r^{2}+(2nd+z-h)^{2}}} \right\} \right]$$

Region 2

From Equation (35)

$$\frac{\partial H_{2\theta}^{e}}{\partial r} = -\frac{H_{2\theta}^{e}}{r} + \frac{I}{4\pi} \left\{ -\frac{z-h}{\sqrt{(r^{2} + (z-h)^{2})^{3}}} + (1-Q) \sum_{n=0}^{\infty} Q^{n} \left[\frac{2nd + z - h}{\sqrt{(r^{2} + 2nd + z - h^{2})^{3}}} + \frac{2nd + z + h}{\sqrt{(r^{2} + 2nd + z + h^{2})^{3}}} \right] \right\}$$

and

$$\frac{\partial H_{2\theta}^{\epsilon}}{\partial z} = \frac{I}{4\pi r} \left\{ -\frac{(z-h)^2}{\sqrt{(r^2 + (z-h)^2)^3}} + \frac{(114)}{\sqrt{(r^2 + 2nd + z - h^2)^3}} + \frac{(2nd + z + h)^2}{\sqrt{(r^2 + 2nd + z + h^2)^3}} \right\}.$$

NON-CONDUCTING BOTTOM (Q=1)

Region 1

From Equation (77)

$$\frac{\partial H_{1\theta}^e}{\partial r} = \frac{I}{4\pi} \left(-\frac{1}{r^2} \left[1 + \frac{z - h}{\sqrt{r^2 + (z - h)^2}} - \frac{2z}{d} \right] - \frac{z - h}{\sqrt{(r^2 + (z - h)^2)^3}} \right) + \frac{\pi^2}{d^2} \sum_{n=1}^{\infty} n K_0(n\pi r/d) \left[\sin\{n\pi (z - h)/d\} + \sin\{n\pi (z + h)/d\} \right] \right)$$
(115)

and

$$\frac{\partial H_{1\theta}^{\epsilon}}{\partial z} = \frac{I}{4\pi r} \left(\frac{1}{\sqrt{r^2 + (z - h)^2}} - \frac{(z - h)^2}{\sqrt{(r^2 + (z - h)^2)^3}} - \frac{2}{d} \right)$$
(116)

$$+r\frac{\pi^2}{d^2}\sum_{n=1}^{\infty}nK_1(n\pi r/d)\left[\cos\{n\pi(z-h)/d\}+\cos\{n\pi(z+h)/d\}\right].$$

Region 2

From Equation (80)

$$\frac{\partial H_{2\theta}^{e}}{\partial r} = -\frac{H_{2\theta}^{e}}{r} - \frac{I}{4\pi} \left[\frac{z - h}{\sqrt{(r^{2} + (z - h)^{2})^{3}}} \right]. \tag{117}$$

and

$$\frac{\partial H_{2\theta}^{\epsilon}}{\partial z} = -\frac{I}{4\pi r} \left[\frac{(z-h)^2}{\sqrt{(r^2 + (z-h)^2)^3}} \right]. \tag{118}$$

PERFECTLY CONDUCTING BOTTOM (Q=-1, REGION 1 ONLY)

From Equation (99)

$$\frac{\partial H_{10}^e}{\partial r} = \frac{I}{4\pi} \left(-\frac{z-h}{r^2 \sqrt{r^2 + (z-h)^2}} - \frac{z-h}{\sqrt{(r^2 + (z-h)^2)^3}} - \frac{2\pi}{d^2} \sum_{n=0}^{\infty} (n+1/2) K_1[(n+1/2)\pi r/d] \right)$$

$$\left\{ \sin[(n+1/2)\pi(z-h)/d] + \sin[(n+1/2)\pi(z+h)/d] \right\}$$
(119)

and

$$\frac{\partial H_{1\theta}^{\epsilon}}{\partial z} = \frac{I}{4\pi r} \left(-\frac{(z-h)^2}{\sqrt{(r^2 + (z-h)^2)^3}} + \frac{1}{\sqrt{r^2 + (z-h)^2}} - \frac{2\pi r}{d^2} \sum_{n=0}^{\infty} (n+1/2)K_1[(n+1/2)\pi r/d] \right)$$

$$\left\{ \cos[(n+1/2)\pi(z-h)/d] + \cos[(n+1/2)\pi(z+h)/d] \right\}.$$
(120)

MAGNETIC FIELD/FIELD GRADIENT GENERATED BY A CABLE TERMINATED IN REGION 1: CABLE-ONLY CONTRIBUTION

The magnetic field/field gradient of a cable carrying a current I, with each end shorted to the medium in region 1, can be constructed as the superposition of the magnetic field/field gradient of an electrode at each cable end point and the Biot-Savart magnetic field/field gradient of the cable current. The configuration is shown in Figure 4.

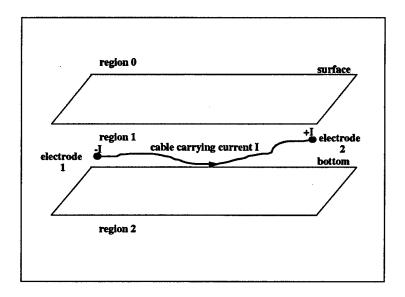


FIGURE 4. CURRENT-CARRYING CABLE/ELECTRODE CONFIGURATION

The electrode contributions to the magnetic field are constructed by means of Equations (34) through (36) with appropriate assignments of geometry and with current signs as indicated in Figure 4. The electrode contributions to the magnetic field gradient tensor are detailed in Equations (105) through (120). The contribution of the cable is obtained by means of a line integral along the cable. In practice, the line integral is approximated as a sum of line integrals over short linear segments. A general representation is now given of the magnetic field vector and gradient tensor for such a segment.

BIOT-SAVART FIELD AND GRADIENT OF A STRAIGHT CABLE SEGMENT

The geometry for the construction is shown in Figure 5. Vector quantities there are indicated with superposed arrows, but in the text they are indicated with boldface type. The various vectors involved are

 $\mathbf{R}_1, \mathbf{R}_2$ locate cable segment end points $(1 \to 2 \text{ positive current flow})$

R locates the field point

 $\mathbf{R_2} - \mathbf{R_1}$ is along the cable segment

$$\hat{\mathbf{l}} = \frac{\mathbf{R}_2 - \mathbf{R}_1}{|\mathbf{R}_2 - \mathbf{R}_1|}, \quad \hat{\mathbf{u}}_1 = \frac{\mathbf{R}_1 - \mathbf{R}}{|\mathbf{R}_1 - \mathbf{R}|}, \quad \text{and} \quad \hat{\mathbf{u}}_2 = \frac{\mathbf{R}_2 - \mathbf{R}}{|\mathbf{R}_2 - \mathbf{R}|} \quad \text{are unit vectors.}$$

With these definitions, the general expression for the magnetic field of the cable segment can be given. This expression is the result of analytically performing the line integral

$$\mathbf{H} = \frac{I}{4\pi} \int_{\mathbf{R}_{1}}^{\mathbf{R}_{2}} \frac{d\mathbf{l'} \times (\mathbf{R} - \mathbf{R'})}{|\mathbf{R} - \mathbf{R'}|^{3}} = \frac{I}{4\pi} \hat{\mathbf{l}} \times (\mathbf{R} - \mathbf{R}_{1}) I_{1}$$
 (121)

$$= \frac{I}{4\pi} \hat{\mathbf{i}} \times (\mathbf{R} - \mathbf{R}_1) \int_{0}^{|\mathbf{R}_1 - \mathbf{R}_2|} \frac{du}{\left(\sqrt{u^2 - 2\hat{\mathbf{i}} \cdot (\mathbf{R} - \mathbf{R}_1)u + |\mathbf{R} - \mathbf{R}_1|^2}\right)^3}$$

over the straight segment, and using some results from vector geometry. The result is

$$I_{1} = \frac{1}{|\mathbf{R} - \mathbf{R}_{1}|^{2}} \left[\frac{\hat{\mathbf{l}} \cdot (\hat{\mathbf{u}}_{2} - \hat{\mathbf{u}}_{1})}{1 - (\hat{\mathbf{l}} \cdot \hat{\mathbf{u}}_{1})^{2}} \right]$$
(122)

and

$$\mathbf{H} = \frac{I}{4\pi |\mathbf{R}_1 - \mathbf{R}|} \hat{\mathbf{u}}_1 \times \hat{\mathbf{I}} \left[\frac{\hat{\mathbf{I}} \cdot (\hat{\mathbf{u}}_2 - \hat{\mathbf{u}}_1)}{1 - (\hat{\mathbf{u}}_1 \cdot \hat{\mathbf{I}})^2} \right]. \tag{123}$$

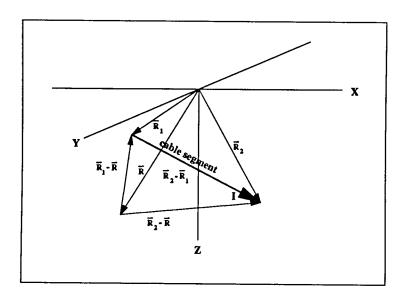


FIGURE 5. CABLE SEGMENT GEOMETRY

The field gradient tensor is best constructed by writing out Equation (121) in component form and taking the appropriate derivatives. Then

$$H_{i} = \frac{I}{4\pi} \varepsilon_{imn} \hat{\mathbf{l}}_{m} (R_{n} - R_{1n}) \int_{0}^{|\mathbf{R}_{1} - \mathbf{R}_{2}|} \frac{du}{\left(\sqrt{u^{2} - 2\hat{\mathbf{l}} \cdot (\mathbf{R} - \mathbf{R}_{1})u + |\mathbf{R} - \mathbf{R}_{1}|^{2}}\right)^{3}}$$
(124)

where the Levi-Civita tensor $\epsilon_{\mbox{\tiny imn}}$ has the properties

$$\varepsilon_{imn} = 1$$
 i,m,n an even permutation of 1,2,3 (125)

 $\varepsilon_{imn} = -1$ i,m,n an odd permutation of 1,2,3

$$\varepsilon_{imn} = 0$$
 otherwise.

This gives the gradient tensor components

$$\frac{\partial H_i}{\partial R_i} = \frac{I}{4\pi} \left\{ \varepsilon_{imn} \hat{\mathbf{l}}_m \delta_{nj} I_1 - 3[\hat{\mathbf{l}} \times (\mathbf{R} - \mathbf{R}_1)]_i \left[(R_j - R_{1j}) I_2 - \hat{\mathbf{l}}_j I_3 \right] \right\}$$
(126)

where

$$I_{2} = \int_{0}^{|\mathbf{R}_{1} - \mathbf{R}_{2}|} \frac{du}{\left(\sqrt{u^{2} - 2\hat{\mathbf{l}} \cdot (\mathbf{R} - \mathbf{R}_{1})u + |\mathbf{R} - \mathbf{R}_{1}|^{2}}\right)^{5}}$$
(127)

and

$$I_{3} = \int_{0}^{|\mathbf{R}_{1} - \mathbf{R}_{2}|} \frac{du \, u}{\left(\sqrt{u^{2} - 2\hat{\mathbf{l}} \cdot (\mathbf{R} - \mathbf{R}_{1})u + |\mathbf{R} - \mathbf{R}_{1}|^{2}}\right)^{5}}.$$
 (128)

Explicitly, define

$$\mathcal{I} = \frac{1}{|\mathbf{R}_1 - \mathbf{R}|^2 [1 - (\hat{\mathbf{l}} \cdot \hat{\mathbf{u}}_1)^2]} \left[\frac{2\hat{\mathbf{l}} \cdot (\hat{\mathbf{u}}_2 - \hat{\mathbf{u}}_1)}{1 - (\hat{\mathbf{l}} \cdot \hat{\mathbf{u}}_1)^2} + \hat{\mathbf{l}} \cdot (\alpha_{12}^2 \hat{\mathbf{u}}_2 - \hat{\mathbf{u}}_1) \right]$$
(129)

$$\mathcal{K} = \frac{1}{|\mathbf{R}_1 - \mathbf{R}|^2} - \frac{\alpha_{12}}{|\mathbf{R}_2 - \mathbf{R}|^2} - (\hat{\mathbf{l}} \cdot \hat{\mathbf{u}}_1) \mathcal{I}$$
(130)

with

$$\alpha_{12} = \frac{|\mathbf{R}_1 - \mathbf{R}|}{|\mathbf{R}_2 - \mathbf{R}|}.$$
 (131)

Then

$$I_2 = \frac{g}{3|\mathbf{R}_1 - \mathbf{R}|^2} \tag{132}$$

$$I_3 = \frac{\mathcal{K}}{3|\mathbf{R}_1 - \mathbf{R}|} \tag{133}$$

and the gradient tensor components can all be written in the compact form

$$\frac{\partial H_i}{\partial R_i} = \frac{I}{4\pi} \left[\varepsilon_{inj} \hat{\mathbf{l}}_m I_1 - (\hat{\mathbf{l}} \times \hat{\mathbf{u}}_1)_i (\hat{\mathbf{l}}_j \mathcal{K} + \hat{\mathbf{u}}_{1j} \mathcal{I}) \right]. \tag{134}$$

Here, it is noted that

$$\nabla \cdot \mathbf{H} = -\frac{I}{4\pi} \{ (\hat{\mathbf{l}} \times \hat{\mathbf{u}}_1) \cdot \hat{\mathbf{l}} + (\hat{\mathbf{l}} \times \hat{\mathbf{u}}_1) \cdot \hat{\mathbf{u}}_1 \mathcal{I} \} \equiv 0.$$
 (135)

GRADIENT MEASUREMENTS: HOUSING EFFECTS

The presence of a distributed current causes the undisturbed gradient tensor to be asymmetric via the relation $\nabla \times \mathbf{H} = \mathbf{J}$. However, any practical gradiometer will be housed in a container that excludes the current from the measurement volume. This will have a profound effect on the measurement, in that it may modify the magnetic field in the enclosure relative to the original field, and it forces the measured gradient tensor to be symmetric, possibly in a way that may be difficult to determine.

Joseph, et. al., 1,2,3 have analyzed the effects of enclosures to determine the relationship between the measured field vector and gradient tensor components and those that exist in the absence of the enclosure. They have given detailed results for spherical and axisymmetric enclosures under the assumption that there are no other boundaries, and that the undisturbed current density J^0 is uniform over the volume occupied by the enclosure.

SPHERICAL ENCLOSURE

For a spherical enclosure, the interior field has the form

$$\mathbf{H} = \mathbf{H}^0 + \mathbf{H}' \tag{136}$$

where H^0 is the field in the absence of the enclosure, and H' is the distortion field, which is related to the current J^0 via

$$\mathbf{H'} = \frac{1}{2} (\mathbf{r} \times \mathbf{J}^0) \tag{137}$$

From this expression, it is clear that the enclosure has no effect on the field at the center of the sphere. Away from the center, there is a nonzero correction term. The expression also can be used to show that the effect of the enclosure on the gradient tensor is to select the symmetric part of the tensor; that is,

$$G_{ij} = \frac{1}{2} (G_{ij}^0 + G_{ji}^0) \tag{138}$$

an expression that holds everywhere within the enclosure. Thus, the measured gradient tensor may be easily calculated in terms of the undistorted tensor.

AXISYMMETRIC ENCLOSURE

In the axisymmetric case, the enclosure affects the field in the following way. On the symmetry axis, the axial distortion field is zero, while the field perpendicular to (athwart) the axis has nontrivial corrections. Off the symmetry axis, both components of the field have nontrivial corrections.

For the gradient tensor, on the symmetry axis, the diagonal components are undistorted, and those involving derivatives with respect to the coordinates perpendicular to the symmetry axis are symmetrized as in the spherical case. Those components involving derivatives with respect to the axial coordinate have corrections that depend on both the ambient current density and the axial enclosure profile, and these corrections may be as large as the undisturbed gradients.

GENERAL ENCLOSURE

In the general nonsymmetric enclosure case, all the gradient tensor components have nontrivial corrections depending on the current density vector and the enclosure shape. The determination of the corrections involves the solution of the system of equations³

$$\mathbf{H}'(\mathbf{r}) = \oint_{S} dS' \frac{1}{4\pi |\mathbf{r} - \mathbf{r}'|} \hat{\mathbf{n}}' \times (\mathbf{J}_{S}^{0} - \sigma \nabla' \phi')$$
 (139)

$$\nabla^2 \phi' = 0 \tag{140}$$

$$\phi' \to 0 \tag{141}$$

and

$$\sigma \hat{\mathbf{n}} \cdot \nabla \phi' = \hat{\mathbf{n}} \cdot \mathbf{J}^0|_{S} \tag{142}$$

where ϕ is the potential due to the presence of the enclosure in the ambient (uniform) current distribution, σ is the medium conductivity, and $\hat{\mathbf{n}}$ is the outward normal to the surface of the enclosure.

The computation of enclosure corrections is beyond the scope of this report. It will be limited to the case of a spherical enclosure. For this case the measured gradient tensor from the electrode-cable combination will have the form

$$G^{s} = \begin{pmatrix} G_{xx}^{e} + G_{xx}^{c} & \frac{1}{2} (G_{xy}^{e} + G_{yx}^{e} + G_{xy}^{c} + G_{yx}^{c}) & \frac{1}{2} (G_{xz}^{e} + G_{xz}^{c} + G_{zx}^{c}) \\ \frac{1}{2} (G_{xy}^{e} + G_{yx}^{e} + G_{yx}^{c} + G_{yx}^{c}) & (G_{yy}^{c} - G_{xx}^{e}) & \frac{1}{2} (G_{yz}^{e} + G_{yz}^{c} + G_{zy}^{c}) \\ \frac{1}{2} (G_{xz}^{e} + G_{xz}^{c} + G_{zx}^{c}) & \frac{1}{2} (G_{yz}^{e} + G_{zy}^{c} + G_{zy}^{c}) & -(G_{xx}^{c} + G_{yy}^{c}) \end{pmatrix}.$$
(143)

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- 2. Joseph, R. I.; Thomas, M. E., Magnetic Field and Field Gradient Corrections within a Nonconducting Sensor Enclosure in a Conducting Fluid-Part II: Vorticity, IEEE Trans. Geosci. Rem. Sens., GE-22, #2, Mar 1984.
- 3. Joseph, R. I., Magnetic Field and Field Gradient Corrections within a Nonconducting Sensor Enclosure in a Conducting Fluid-Part III: Current Exclusion Contribution for an Arbitrary Axisymmetric Enclosure, IEEE Trans. Geosci. Rem. Sens., GE-22, #4, Jul 1984.

APPENDIX A

TRANSERA HIGH TECH BASIC CODES FOR REGION 1

CURRENT DENSITY CODE

```
SUB Jelectrode(R(*),Re(*),Db,S,Sb,I,Jay(*),Err)
20
     X=R(1)
30
     Y=R(2)
     Z=R(3)
40
50
     Xe=Re(1)
60
     Ye=Re(2)
70
     Ze=Re(3)
80
     Dx=X-Xe
     Dv=Y-Ye
90
      IF SOR((Dx*Dx+Dy*Dy)/(X*X+Y*Y+Xe*Xe+Ye*Ye))<1.E-12 THEN
100
110
       Jav(1)=0
120
       Jay(2)=0
       Jay(3)=0
GOTO 1560
130
140
      END IF
150
160
170
        !This program calculates the current density within the upper
        !layer of a two-layer conductor, bounded above by air, due to
180
190
        an electrode injecting a current I into that layer. X.Y. and
200
        !Z are the coordinates (meters) of the field point in a coordi-
210
        !nate system whose origin is at the surface. Xe, Ye, and Ze are
        !the coordinates (meters) of the electrode. Db is the depth to
220
230
        !the conductor-conductor boundary below the air-conductor bound-
240
        lary. S is the conductivity (Siemens/meter) of the upper conduct-
250
        ling layer and Sb is that for the lower layer (for Sb=0, corre-
260
        !sponding to an insulating bottom, or Sb<0, a perfectly conducting
270
        !bottom, alternate series expressions are used). Jay(*) is the
280
        !three-component field vector in amperes/meter^2. Err is the size
290
        !of the summand relative to the sum when summation ceases. Note
300
        !that I is positive if current enters the medium from the electrode
310
        !and negative otherwise.
320
330
      OPTION BASE 1
340
      IF Sb>0 THEN
350
       Q=(S-Sb)/(S+Sb)
      ELSE
360
370
       IF Sb=0 THEN
380
        Q=1
390
       ELSE
400
        O = -1
410
       END IF
420
      END IF
430
      X2=(X-Xe)*(X-Xe)
440
     Y2=(Y-Ye)*(Y-Ye)
450
      R0=SOR(X2+Y2)
460
      R03=R0*R0*R0
```

```
470
      Rm=SQR(R0*R0+(Z-Ze)*(Z-Ze))
480
      Rm3=Rm*Rm*Rm
490
      Rp=SQR(R0*R0+(Z+Ze)*(Z+Ze))
500
      Rp3=Rp*Rp*Rp
510
      IF ABS(O)<1 THEN
520
       Smxy=1/Rm3+1/Rp3
530
       Smz=(Z-Ze)/Rm3+(Z+Ze)/Rp3
540
       Qn=Q
550
       N=1
560
       Zmm=2*N*Db-Z-Ze
570
       Zpp=2*N*Db+Z+Ze
580
       Zmp=2*N*Db-Z+Ze
590
       Zpm=2*N*Db+Z-Ze
600
       Rmm = SQR(R0*R0+Zmm*Zmm)
610
       Rpp=SQR(R0*R0+Zpp*Zpp)
620
       Rmp = SQR(R0*R0+Zmp*Zmp)
630
       Rpm = SQR(R0*R0+Zpm*Zpm)
      Rmm3=Rmm*Rmm*Rmm
640
650
      Rpp3=Rpp*Rpp*Rpp
660
      Rmp3=Rmp*Rmp*Rmp
670
      Rpm3=Rpm*Rpm*Rpm
      Intz=Qn*(-Zmm/Rmm3+Zpp/Rpp3-Zmp/Rmp3+Zpm/Rpm3)
680
690
      Intxy=Qn*(1/Rmm3+1/Rpp3+1/Rmp3+1/Rpm3)
700
      Smz=Smz+Intz
710
      Smxy=Smxy+Intxy
720
      IF N>4 THEN
730
       IF ABS(Intz/Smz)<Err THEN
740
        IF ABS(Intxy/Smxy)<Err THEN
750
         GOTO 820
760
        END IF
770
       END IF
780
      END IF
790
      N=N+1
800
      Qn=Q*On
810
      GOTO 560
820
      Jay(3)=I*Smz/4/PI
830
      Jay(1)=(X-Xe)*I*Smxy/4/PI
840
      Jay(2)=(Y-Ye)*I*Smxy/4/PI
850
     ELSE
860
      Zm=Z-Ze
870
      Zp=Z+Ze
880
      Smxy=0
890
      Smz=0
900
      Fxy=0
910
      Fz=0
920
      IF Q=1 THEN
930
       N=1
940
       CALL K0(N*PI*R0/Db,K0)
950
       CALL K1(N*PI*R0/Db,K1)
960
       Intxy=N*K1*(COS(N*PI*Zm/Db)+COS(N*PI*Zp/Db))
970
       Intz=N*K0*(SIN(N*PI*Zm/Db)+SIN(N*PI*Zp/Db))
980
       Smxy=Smxy+Intxy
```

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```
990
        Smz=Smz+Intz
1000
        IF N>4 THEN
         IF ABS(Smxy)=0 THEN
1010
1020
          Fxy=1
         ELSE
1030
          IF ABS(Intxy)/ABS(Smxy)<Err THEN
1040
1050
1060
          END IF
1070
         END IF
1080
         IF ABS(Smz)=0 THEN
1090
          Fz=1
1100
         ELSE
1110
          IF ABS(Intz)/ABS(Smz)<Err THEN
1120
1130
          END IF
1140
         END IF
1150
         IF Fxy+Fz>1 THEN GOTO 1190
1160
         N=N+1
1170
         GOTO 940
1180
        END IF
1190
        Jay(3)=I/2/Db/Db*Smz
1200
        Jfac=I/(2*PI*R0*R0*Db)*(1+PI*R0/Db*Smxy)
1210
        Jay(1)=(X-Xe)*Jfac
1220
        Jay(2)=(Y-Ye)*Jfac
1230
       ELSE
1240
        N=0
1250
        CALL K0((N+.5)*PI*R0/Db,K0)
1260
        CALL K1((N+.5)*PI*R0/Db,K1)
1270
        Intxy=(N+.5)*K1*(COS((N+.5)*PI*Zm/Db)+COS((N+.5)*PI*Zp/Db))
1280
        Intz=(N+.5)*K0*(SIN((N+.5)*PI*Zm/Db)+SIN((N+.5)*PI*Zp/Db))
1290
        Smxy=Smxy+Intxy
        Smz=Smz+Intz
1300
1310
        IF N>4 THEN
1320
         IF ABS(Smxy)=0 THEN
1330
          Fxy=1
1340
         ELSE
1350
          IF ABS(Intxy)/ABS(Smxy)<Err THEN
1360
           Fxy=1
1370
          END IF
1380
         END IF
1390
         IF ABS(Smz)=0 THEN
1400
          Fz=1
1410
         ELSE
1420
          IF ABS(Intz)/ABS(Smz)<Err THEN
1430
           Fz=1
1440
          END IF
1450
         END IF
1460
         IF Fxy+Fz>1 THEN GOTO 1500
1470
         N=N+1
1480
         GOTO 1250
1490
        END IF
1500
        Jay(3)=I/2/Db/Db*Smz
```

```
1510 Jfac=I/(2*R0*Db*Db)
1520 Jay(1)=(X-Xe)*Jfac*Smxy
1530 Jay(2)=(Y-Ye)*Jfac*Smxy
1540 END IF
1550 END IF
1560 SUBEND
```

ELECTRODE MAGNETIC FIELD CODE

```
10
     SUB Helectrode(R(*),Re(*),Db,S,Sb,I,Aitch(*),Err)
 20
      X=R(1)
 30
      Y=R(2)
 40
      Z=R(3)
 50
      Xe=Re(1)
60
      Ye=Re(2)
70
      Ze=Re(3)
80
      Dx=X-Xe
90
      Dy=Y-Ye
100
      IF SQR((Dx*Dx+Dy*Dy)/(X*X+Y*Y+Xe*Xe+Ye*Ye))<1.E-12 THEN
110
        Aitch(1)=0
120
        Aitch(2)=0
130
        Aitch(3)=0
140
        GOTO 1080
150
      END IF
160
170
        !This program calculates the magnetic field within the upper
180
        !layer of a two-layer conductor, bounded above by air, due to
        !an electrode injecting a current I into that layer. X,Y, and
190
200
        !Z are the coordinates (meters) of the field point in a coordi-
210
        !nate system whose origin is at the surface. Xe, Ye, and Ze are
220
        !the coordinates (meters) of the electrode. Db is the depth to
230
        !the conductor-conductor boundary below the air-conductor bound-
240
        lary. S is the conductivity (Siemens/meter) of the upper conduct-
250
        !ing layer and Sb is that for the lower layer(for Sb=0, corre-
260
        !sponding to an insulating bottom, or Sb<0, a perfectly conducting
        !bottom, alternate series expressions are used). Aitch(*) is
270
        !the three-component field vector(amperes/meter). Err is the size
280
290
        !of the summand relative to the sum when summation ceases. Note
300
        !that I is positive if current enters the medium from the electrode
310
        land negative otherwise.
320
330
      OPTION BASE 1
340
      IF Sb>0 THEN
350
       Q=(S-Sb)/(S+Sb)
360
      ELSE
370
       IF Sb=0 THEN
380
        O=1
       ELSE
390
        Q = -1
400
410
       END IF
```

```
420
     END IF
430
     X2=(X-Xe)*(X-Xe)
440
     Y2=(Y-Ye)*(Y-Ye)
450
    R0=SOR(X2+Y2)
460
     R03=R0*R0*R0
470
     Rp = SOR(R0*R0+(Z+Ze)*(Z+Ze))
480
     R3=Rp*Rp*Rp
490
     IF ABS(O)<1 THEN
500
      Sm=1-(Z+Ze)/Rp
510
      On=Q
520
      N=1
530
      Zmm=2*N*Db-Z-Ze
540
      Zpp=2*N*Db+Z+Ze
      Zmp=2*N*Db-Z+Ze
550
560
      Zpm=2*N*Db+Z-Ze
      Rmm = SOR(R0*R0+Zmm*Zmm)
570
580
      Rpp=SQR(R0*R0+Zpp*Zpp)
590
      Rmp=SQR(R0*R0+Zmp*Zmp)
600
      Rpm=SQR(R0*R0+Zpm*Zpm)
610
      Int=Qn*(Zmm/Rmm-Zpp/Rpp+Zmp/Rmp-Zpm/Rpm)
620
      Sm=Sm+Int
630
      IF N>2 THEN
640
       IF ABS(Int/Sm)<Err THEN
650
        Sm=I*Sm/(4*PI*R0)
660
        GOTO 1050
670
       END IF
680
      END IF
690
      N=N+1
700
      On=O*On
710
      GOTO 530
720
     ELSE
      Sm=0
730
740
      Zm=Z-Ze
      Zp=Z+Ze
750
760
      Rm = SOR(R0*R0+Zm*Zm)
770
      IF O=1 THEN
       N=1
780
790
       CALL K1(N*PI*R0/Db,K1)
800
       Int=K1*(SIN(N*PI*Zm/Db)+SIN(N*PI*Zp/Db))
810
       Sm=Sm+Int
820
       IF N>=2 THEN
830
        IF ABS(Int)/ABS(Sm)<Err THEN 880
840
       ELSE
        N=N+1
850
860
        GOTO 790
870
       END IF
880
       Sm=1-2*Z/Db+Zm/Rm+PI*R0/Db*Sm
890
       Sm=I*Sm/(4*PI*R0)
900
      ELSE
910
       N=0
920
       CALL K1((N+.5)*PI*R0/Db,K1)
       Int=K1*(SIN((N+.5)*PI*Zm/Db)+SIN((N+.5)*PI*Zp/Db))
930
```

```
940
       Sm=Sm+Int
950
       IF N>=2 THEN
960
        IF ABS(Int)/ABS(Sm)<Err THEN 1010
970
       ELSE
980
        N=N+1
990
        GOTO 920
1000
        END IF
1010
        Sm=1+Zm/Rm-2*R0/Db*Sm
1020
        Sm=I*Sm/(4*PI*R0)
1030
       END IF
1040
     END IF
1050 Aitch(1)=(Ye-Y)*Sm/R0
1060 Aitch(2)=(X-Xe)*Sm/R0
1070 \text{ Aitch(3)=0}
1080 SUBEND
```

ELECTRODE MAGNETIC FIELD GRADIENT CODE

```
SUB Gelectrode(R(*),Re(*),Db,S,Sb,I,G(*),Err)
 10
 20
      OPTION BASE 1
 30
      DIM H(3)
 40
      X=R(1)
 50
      Y=R(2)
 60
      Z=R(3)
 70
      Xe=Re(1)
80
      Ye=Re(2)
90
      Ze=Re(3)
100
        !This program calculates the magnetic field gradient within the upper
110
        !layer of a two-layer conductor, bounded above by air, due to
120
        !an electrode injecting a current I into that layer. X,Y, and
130
        !Z are the coordinates (meters) of the field point in a coordi-
140
        !nate system whose origin is at the surface. Xe, Ye, and Ze are
150
        !the coordinates (meters) of the electrode. Db is the depth to
160
        !the conductor-conductor boundary below the air-conductor bound-
170
        lary. S is the conductivity (Siemens/meter) of the upper conduct-
180
        !ing layer and Sb is that for the lower layer(for Sb=0, corre-
190
        !sponding to an insulating bottom, or Sb<0, a perfectly conducting
200
        !bottom, alternate series expressions are used). G(*) is the
210
        !3x3 magnetic gradient tensor(amperes/meter^2). Err is the size
220
        lof the summand relative to the sum when summation ceases. Note
230
        !that I is positive if current enters the medium from the electrode
240
250
        land negative otherwise.
260
270
      IF Sb>0 THEN
280
       Q=(S-Sb)/(S+Sb)
290
      ELSE
300
       IF Sb=0 THEN
310
        Q=1
320
       ELSE
```

```
330
       0 = -1
340
      END IF
350
     END IF
360
     X2=(X-Xe)*(X-Xe)
370
     Y2=(Y-Ye)*(Y-Ye)
380
     Xy=(X-Xe)*(Y-Ye)
390
     R0=SQR(X2+Y2)
400
     R02=R0*R0
410
     R03=R0*R0*R0
420
     Rp=SQR(R0*R0+(Z+Ze)*(Z+Ze))
430
     R3=Rp*Rp*Rp
440
     IF ABS(Q)<1 THEN
450
      Smtr=(Z+Ze)/R3
460
      Smtz=(Z+Ze)*(Z+Ze)/R3-1/Rp
470
      On=O
480
      N=1
490
      Zmm=2*N*Db-Z-Ze
500
      Zmm2=Zmm*Zmm
      Zpp=2*N*Db+Z+Ze
510
520
      Zpp2=Zpp*Zpp
530
      Zmp=2*N*Db-Z+Ze
      Zmp2=Zmp*Zmp
540
550
      Zpm=2*N*Db+Z-Ze
560
      Zpm2=Zpm*Zpm
570
      Rmm = SQR(R0*R0+Zmm*Zmm)
580
      Rmm3=Rmm*Rmm*Rmm
590
      Rpp=SQR(R0*R0+Zpp*Zpp)
      Rpp3=Rpp*Rpp*Rpp
600
610
      Rmp=SQR(R0*R0+Zmp*Zmp)
620
      Rmp3=Rmp*Rmp*Rmp
630
      Rpm=SQR(R0*R0+Zpm*Zpm)
640
      Rpm3=Rpm*Rpm*Rpm
650
      Inttr=Qn*(-Zmm/Rmm3+Zpp/Rpp3-Zmp/Rmp3+Zpm/Rpm3)
660
      Inttz=On*(Zmm2/Rmm3+Zpp2/Rpp3+Zmp2/Rmp3+Zpm2/Rpm3)
670
      Inttz=Inttz+Qn*(-1/Rmm-1/Rpp-1/Rmp-1/Rpm)
680
      Smtr=Smtr+Inttr
690
      Smtz=Smtz+Inttz
700
      IF N>2 THEN
710
       IF ABS(Inttr/Smtr)<Err THEN
720
        IF ABS(Inttz/Smtz)<Err THEN
730
         Smtr=I*Smtr/(4*PI)
740
         Smtz=I*Smtz/(4*PI*R0)
750
         GOTO 1290
        END IF
760
770
       END IF
780
      END IF
790
      N=N+1
800
      On=O*On
810
      GOTO 490
820
     ELSE
830
      Smtr=0
840
      Smtz=0
```

```
850
       Zm=Z-Ze
860
       Zp=Z+Ze
870
       Rm = SQR(R0*R0+Zm*Zm)
880
       Rm3=Rm*Rm*Rm
890
       IF O=1 THEN
900
        N=1
910
        CALL K0(N*PI*R0/Db,K0)
920
        Inttr=N*K0*(SIN(N*PI*Zm/Db)+SIN(N*PI*Zp/Db))
930
        Smtr=Smtr+Inttr
940
        CALL K1(N*PI*R0/Db,K1)
950
        Inttz=N*K1*(COS(N*PI*Zm/Db)+COS(N*PI*Zp/Db))
960
        Smtz=Smtz+Inttz
970
        IF N>=2 THEN
980
         IF ABS(Inttr)/ABS(Smtr)<Err THEN
990
          IF ABS(Inttz)/ABS(Smtz)<Err THEN
1000
            GOTO 1060
1010
          END IF
1020
         END IF
1030
        END IF
1040
        N=N+1
1050
        GOTO 910
1060
        Smtr=I*(-(1+Zm/Rm-2*Z/Db)/R02-Zm/Rm3+PI*PI/Db/Db*Smtr)/4/PI
1070
        Smtz=I*(-2/Db-Zm*Zm/Rm3+1/Rm+PI*PI*R0*Smtz/Db/Db)/(4*PI*R0)
1080
       ELSE
1090
        N=0
1100
        CALL K0((N+.5)*PI*R0/Db,K0)
1110
        Inttr=(N+.5)*K0*(SIN((N+.5)*PI*Zm/Db)+SIN((N+.5)*PI*Zp/Db))
1120
        Smtr=Smtr+Inttr
1130
        CALL K1((N+.5)*PI*R0/Db,K1)
1140
        Inttz=(N+.5)*K1*(COS((N+.5)*PI*Zm/Db)+COS((N+.5)*PI*Zp/Db))
1150
        Smtz=Smtz+Inttz
1160
        IF N>=2 THEN
1170
         IF ABS(Inttr)/ABS(Smtr)<Err THEN
1180
         'IF ABS(Inttz)/ABS(Smtz)<Err THEN
1190
           GOTO 1250
1200
          END IF
         END IF
1210
1220
        END IF
1230
        N=N+1
1240
        GOTO 1100
1250
        Smtr=-I*(Zm/Rm/R02+Zm/Rm3+2*PI*Smtr/Db/Db)/4/PI
1260
        Smtz=I*(-Zm*Zm/Rm3+1/Rm-2*PI*R0*Smtz/Db/Db)/(4*PI*R0)
1270
       END IF
1280 END IF
1290 CALL Helectrode(R(*),Re(*),Db,S,Sb,I,H(*),Err)
1300 Ht=(X-Xe)*H(2)/R0-(Y-Ye)*H(1)/R0
1310 IF ABS(O)<1 THEN
1320
      Smtr=Smtr-Ht/R0
1330 END IF
1340 G(1,1)=Xy*(Ht-R0*Smtr)/R03
1350 G(2,2)=-G(1,1)
1360 G(3,3)=0
```

```
1370 G(3,1)=0

1380 G(3,2)=0

1390 G(1,2)=-(X2*Ht+R0*Y2*Smtr)/R03

1400 G(2,1)=(Y2*Ht+R0*X2*Smtr)/R03

1410 G(1,3)=-(Y-Ye)*Smtz/R0

1420 G(2,3)=(X-Xe)*Smtz/R0

1430 SUBEND
```

BIOT-SAVART MAGNETIC FIELD CODE

```
SUB Hbiotsavrt(I,R1(*),R2(*),R(*),H(*))
10
20
     OPTION BASE 1
30
     DIM X1(3),X2(3),X12(3),L(3),U1(3),U2(3)
40
50
      !This program calculates the magnetic field H(*) (amperes/meter)
60
      !at the point R(*) (meters), due to a straight wire segment
70
      !whose end points are R1(*) and R2(*) (meters), and in which
80
      !the current flows from R1(*) to R2(*).
90
100
     X1(1)=R1(1)-R(1)
     X1(2)=R1(2)-R(2)
110
120
     X1(3)=R1(3)-R(3)
130
     X2(1)=R2(1)-R(1)
140
     X2(2)=R2(2)-R(2)
150
     X2(3)=R2(3)-R(3)
160
     X12(1)=R2(1)-R1(1)
170
     X12(2)=R2(2)-R1(2)
180
     X12(3)=R2(3)-R1(3)
     R1m = SQR(DOT(X1,X1))
190
200
     R2m = SQR(DOT(X2,X2))
     R12m = SQR(DOT(X12,X12))
210
220
     MAT L = (1/R12m)*X12
230
     MAT U1 = (1/R1m)*X1
240
     MAT U2 = (1/R2m)*X2
250
     N=DOT(L,U1)-DOT(L,U2)
260
     D=1-DOT(L,U1)*DOT(L,U1)
270
     Fac=(I*N)/(4*PI*R1m*D)
280
     H(1)=L(2)*U1(3)-L(3)*U1(2)
290
     H(2)=L(3)*U1(1)-L(1)*U1(3)
300
     H(3)=L(1)*U1(2)-L(2)*U1(1)
310
     MAT H= (Fac)*H
320 SUBEND
```

BIOT-SAVART MAGNETIC FIELD GRADIENT CODE

```
10 SUB Gbiotsavrt(I,R1(*),R2(*),R(*),G(*))
20 OPTION BASE 1
30 DIM X1(3),X2(3),X12(3),L(3),U1(3),U2(3)
```

```
40
50
       !This program calculates the magnetic field gradient tensor
60
       !G(*) (ampere/meter^2) at the point R(*) (meters), due to a
70
       !straight wire segment whose end points are R1(*) and R2(*)
80
       !(meters) and in which positive current I flows from R1(*)
90
       !to R2(*).
100
110
      X1(1)=R1(1)-R(1)
120
      X1(2)=R1(2)-R(2)
130
      X1(3)=R1(3)-R(3)
140
      X2(1)=R2(1)-R(1)
150
      X2(2)=R2(2)-R(2)
160
      X2(3)=R2(3)-R(3)
170
      X12(1)=R2(1)-R1(1)
180
      X12(2)=R2(2)-R1(2)
190
      X12(3)=R2(3)-R1(3)
200
      R1m = SOR(DOT(X1,X1))
210
      R2m = SOR(DOT(X2,X2))
220
      R12m = SQR(DOT(X12,X12))
230
      MAT L=(1/R12m)*X12
240
      MAT U1 = (1/R1m) * X1
250
      MAT U2=(1/R2m)*X2
260
      N=DOT(L,U1)-DOT(L,U2)
270
      D=1-DOT(L,U1)*DOT(L,U1)
280
      I1=-N/D/R1m/R1m
290
      A12=R1m/R2m
300
      I2=(-2*N/D+A12*A12*DOT(L,U2)-DOT(L,U1))/D/R1m/R1m
      I3=1/R1m/R1m-A12/R2m/R2m-DOT(L,U1)*I2
310
320
      Gfac=I/4/PI
      G(1,1)=Gfac*(-L(2)*U1(3)+L(3)*U1(2))*(L(1)*I3+U1(1)*I2)
330
340
      G(2,2)=Gfac*(-L(3)*U1(1)+L(1)*U1(3))*(L(2)*I3+U1(2)*I2)
350
      G(3,3)=-G(1,1)-G(2,2)
      G(1,2)=Gfac*(-L(3)*I1+(-L(2)*U1(3)+L(3)*U1(2))*(L(2)*I3+U1(2)*I2))
360
     G(2,1)=Gfac*(L(3)*I1+(-L(3)*U1(1)+L(1)*U1(3))*(L(1)*I3+U1(1)*I2))
370
380
     G(1,3)=Gfac*(L(2)*I1+(-L(2)*U1(3)+L(3)*U1(2))*(L(3)*I3+U1(3)*I2))
     G(3,1) = Gfac*(-L(2)*I1+(-L(1)*U1(2)+L(2)*U1(1))*(L(1)*I3+U1(1)*I2))
390
400
     G(2,3)=Gfac*(-L(1)*I1+(-L(3)*U1(1)+L(1)*U1(3))*(L(3)*I3+U1(3)*I2))
     G(3,2)=Gfac*(L(1)*I1+(-L(1)*U1(2)+L(2)*U1(1))*(L(2)*I3+U1(2)*I2))
410
420 SUBEND
```

MODIFIED BESSEL FUNCTION CODES

```
10 SUB IO(X,IO)
20 !
30 !calculates the modified bessel function IO(x) for real x>=0
40 !
50 OPTION BASE 1
60 DIM A(9),T(9)
70 MAT A=(0)
80 MAT T=(0)
```

```
90
     U=X/3.75
100
      IF U<=1 THEN
110
       A(1)=1
120
       A(2)=3.5156229
130
       A(3)=3.0899424
       A(4)=1.2067492
140
150
       A(5)=.2659732
       A(6)=.0360768
160
170
       A(7)=.0045813
180
       T(1)=1
190
       T(2)=U*U
200
       T(3)=T(2)*T(2)
210
       T(4)=T(2)*T(3)
220
       T(5)=T(3)*T(3)
       T(6)=T(2)*T(5)
230
240
       T(7)=T(4)*T(4)
250
       I0=DOT(A,T)
260
      ELSE
270
       A(1)=.39894228
280
       A(2)=.01328592
290
       A(3)=.00225319
300
       A(4) = -.00157565
310
       A(5)=.00916281
320
       A(6) = -.02057706
330
       A(7)=.02635537
340
       A(8) = -.01647633
350
       A(9)=.00392377
360
       T(1)=1
370
       T(2)=1/U
380
       T(3)=T(2)*T(2)
390
       T(4)=T(2)*T(3)
       T(5)=T(3)*T(3)
400
       T(6)=T(2)*T(5)
410
420
       T(7)=T(4)*T(4)
430
       T(8)=T(2)*T(7)
440
       T(9)=T(5)*T(5)
450
      I0=EXP(X)/SQR(X)*DOT(A,T)
460
     END IF
470 SUBEND
480 SUB I1(X,I1)
490
500
     !calculates the modified bessel function I1(x) for real x>=0
510
520
     OPTION BASE 1
     DIM A(9),T(9)
530
540
     MAT A=(0)
     MATT=(0)
550
560
     U=X/3.75
570
     IF U<=1 THEN
580
      A(1)=.5
      A(2)=.87890594
590
```

```
600
       A(3)=.51498869
610
       A(4)=.15084934
620
       A(5)=.02658733
630
       A(6)=.00301532
640
       A(7)=.00032411
650
       T(1)=1
660
       T(2)=U*U
670
       T(3)=T(2)*T(2)
680
       T(4)=T(2)*T(3)
690
       T(5)=T(3)*T(3)
700
       T(6)=T(2)*T(5)
710
       T(7)=T(4)*T(4)
720
       I1=X*DOT(A,T)
730
      ELSE
740
       A(1)=.39894228
750
       A(2) = -.03988024
       A(3) = -.00362018
760
770
       A(4)=.00163801
780
       A(5) = -.01031555
790
       A(6)=.02282967
800
       A(7) = -.02895312
810
       A(8) = .01787654
820
       A(9) = -.00420059
       T(1)=1
830
840
       T(2)=1/U
850
       T(3)=T(2)*T(2)
860
       T(4)=T(2)*T(3)
870
       T(5)=T(3)*T(3)
880
       T(6)=T(2)*T(5)
890
       T(7)=T(4)*T(4)
900
       T(8)=T(2)*T(7)
910
       T(9)=T(5)*T(5)
920
       I1=EXP(X)/SQR(X)*DOT(A,T)
930
     END IF
940 SUBEND
950 SUB K0(X,K0)
960
970
     !calculates the modified bessel function K0(x) for real x>=0
980
990
     OPTION BASE 1
1000 DIM A(7),T(7)
1010
      MAT A=(0)
1020
      MATT=(0)
1030
      U=X/2
1040
      IF U<=1 THEN
1050
       A(1) = -.57721566
1060
       A(2)=.42278420
1070
       A(3)=.23069756
1080
       A(4)=.03488590
1090
       A(5)=.00262698
1100
       A(6)=.00010750
1110
       A(7)=.00000740
```

```
1120
       T(1)=1
1130
       T(2)=U*U
1140
       T(3)=T(2)*T(2)
1150
       T(4)=T(2)*T(3)
       T(5)=T(3)*T(3)
1160
       T(6)=T(2)*T(5)
1170
1180
       T(7)=T(4)*T(4)
1190
       CALL I0(X,I)
       K0=-LOG(U)*I+DOT(A,T)
1200
1210
      ELSE
1220
       A(1)=1.25331414
1230
       A(2)=-.07832358
1240
       A(3)=.02189568
1250
       A(4) = -.01062446
1260
       A(5)=.00587872
1270
       A(6)=-.00251540
       A(7)=.00053208
1280
       T(1)=1
1290
1300
       T(2)=1/U
       T(3)=T(2)*T(2)
1310
1320
       T(4)=T(2)*T(3)
1330
       T(5)=T(3)*T(3)
1340
       T(6)=T(2)*T(5)
1350
       T(7)=T(4)*T(4)
1360
       K0=EXP(-X)/SOR(X)*DOT(A,T)
1370 END IF
1380 SUBEND
1390 SUB K1(X,K1)
1400 !
1410 !calculates the modified bessel function K1(x) for real x>=0
1420
1430 OPTION BASE 1
1440 DIM A(7),T(7)
1450 MAT A=(0)
1460 MAT T=(0)
1470
      U=X/2
1480
      IF U<=1 THEN
1490
       A(1)=1
1500
       A(2)=.15443144
1510
       A(3)=-.67278579
1520
       A(4)=-.18156897
1530
       A(5)=-.01919402
1540
       A(6) = -.00110404
1550
       A(7) = -.00004686
1560
       T(1)=1
       T(2)=U*U
1570
1580
       T(3)=T(2)*T(2)
1590
       T(4)=T(2)*T(3)
1600
       T(5)=T(3)*T(3)
1610
       T(6)=T(2)*T(5)
1620
       T(7)=T(4)*T(4)
1630
       CALL I1(X,I)
```

```
K1=LOG(U)*I+DOT(A,T)/X
1640
1650 ELSE
1660
       A(1)=1.25331414
1670
       A(2)=.23498619
1680
       A(3) = -.03655620
1690
       A(4)=.01504268
1700
       A(5) = -.00780353
1710
       A(6)=.00325614
1720
       A(7) = -.00068245
1730
       T(1)=1
       T(2)=1/U
1740
       T(3)=T(2)*T(2)
1750
       T(4)=T(2)*T(3)
1760
1770
       T(5)=T(3)*T(3)
1780
       T(6)=T(2)*T(5)
1790
       T(7)=T(4)*T(4)
      K1=EXP(-X)/SQR(X)*DOT(A,T)
1800
1810 END IF
1820 SUBEND
```

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